

ANSWER KEY — ROTATION DAY 12

Full Unit Review | For teacher use only

1. QUICK RETRIEVAL — FILL THE GAPS

- (a) $\tau = rF \sin \theta$
(b) I for a solid disk = $\frac{1}{2}MR^2$
(c) For rolling without slipping, $v_{\text{cm}} = \omega r$
(d) Conditions for static equilibrium: $\sum F = 0$ AND $\sum \tau = 0$
(e) Angular momentum is conserved when $\sum \tau_{\text{ext}} = 0$
(f) In the ramp race, the **solid sphere** always wins because it has the lowest $C = I/(mr^2) = 2/5$, so the least energy goes to rotation.

2. KINEMATICS + DYNAMICS

- (a) $I = \frac{1}{2}MR^2 = \frac{1}{2}(3.0)(0.20^2) = 0.060 \text{ kg}\cdot\text{m}^2$
(b) $\tau = FR = (15)(0.20) = 3.0 \text{ N}\cdot\text{m}$
(c) $\alpha = \tau/I = 3.0/0.060 = 50 \text{ rad/s}^2$
(d) $\omega = \alpha t = (50)(4.0) = 200 \text{ rad/s}$
(e) $K = \frac{1}{2}I\omega^2 = \frac{1}{2}(0.060)(200^2) = 1200 \text{ J}$

3. STATICS — BEAM

- (a) Torques about hinge:
 $T \cdot L \sin 50^\circ = M_{\text{beam}}g(L/2) + mg \cdot d$
 $T(4.0) \sin 50^\circ = (20)(9.8)(2.0) + (10)(9.8)(3.0) = 392 + 294 = 686 \text{ N}\cdot\text{m}$
 $T = 686/(4.0 \times 0.766) = 686/3.06 = 224 \text{ N}$
(b) $H_x = T \cos 50^\circ = 224(0.643) = 144 \text{ N}$
 $H_y = (M + m)g - T \sin 50^\circ = 294 - 172 = 122 \text{ N}$

4. ROLLING — SPHERE VS CYLINDER

- Using $v = \sqrt{2gh/(1+C)}$ with $h = 2.5 \text{ m}$:
Sphere ($C = 2/5$): $v = \sqrt{2(9.8)(2.5)/1.4} = \sqrt{35.0} = 5.92 \text{ m/s}$
Cylinder ($C = 1/2$): $v = \sqrt{2(9.8)(2.5)/1.5} = \sqrt{32.7} = 5.72 \text{ m/s}$
Sphere reaches the bottom first. Lower $C \rightarrow$ less energy diverted to rotation \rightarrow faster translational speed. Mass and radius don't matter — only C .

5. FULL AP FRQ — PULLEY SYSTEM

- (a) FBDs:
 m_1 : T_1 right, N up, m_1g down. m_2 : T_2 up, m_2g down. Pulley: T_1 and T_2 on rim (opposite sides), pivot force at center.
(b) m_1 : $T_1 = m_1a = 4.0a$
 m_2 : $m_2g - T_2 = m_2a \rightarrow 58.8 - T_2 = 6.0a$
(c) Pulley: $(T_2 - T_1)R = I\alpha = \frac{1}{2}MR^2 \cdot (a/R)$
 $T_2 - T_1 = \frac{1}{2}Ma = \frac{1}{2}(2.0)a = 1.0a$
(d) Add all three equations: $m_2g = (m_1 + m_2 + \frac{1}{2}M)a$
 $a = 58.8/(4.0 + 6.0 + 1.0) = 58.8/11.0 = 5.3 \text{ m/s}^2$
Check: $T_1 = 21.4 \text{ N}$, $T_2 = 26.7 \text{ N}$. $T_2 > T_1 \checkmark$ (net torque accelerates the pulley).

(e) **The pulley's angular velocity remains constant** (ignoring friction). With no string, there is no net torque on the pulley, so angular momentum is conserved and ω doesn't change.

6. COMMON MISTAKES — ERROR ANALYSIS

Mistake 1: Wrong. If the pulley has mass (and therefore rotational inertia), the string must exert different tensions on each side to produce the net torque needed to angularly accelerate the pulley. $T_1 = T_2$ is only true for a massless, frictionless pulley.

Mistake 2: Backwards reasoning. Higher rotational inertia means more energy goes INTO rotation, leaving LESS for translation. The hoop is slower, not faster. The disk (lower C) wins the ramp race.