

OSCILLATIONS DAY 4: GRAPHS & THE SMALL ANGLE APPROXIMATION

Physics in the Wild: Reading Oscillations

Doctors read EKGs (heart oscillations). Seismologists read seismograms (earth oscillations). Audio engineers read waveforms (sound oscillations). All of them are reading SHM graphs.

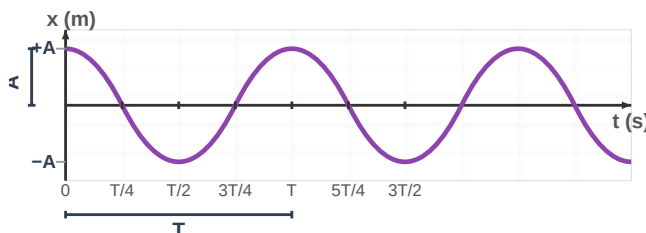
Emergence thread: *Universality — the same sinusoidal pattern appears in springs, pendulums, sound, light, molecular vibrations, and electrical circuits. When many different systems produce the exact same pattern, that pattern is emergent — it belongs to the math, not to any one physical system.*

POSITION VS TIME

$$x(t) = A \cos\left(\frac{2\pi t}{T}\right)$$

A = amplitude (max displacement), **T** = period, **f** = $1/T$

If released from maximum positive displacement, the object starts at $x = +A$ when $t = 0$.



WE DO Exercise 1: Reading the Graph

From the graph above, identify: (a) The amplitude **A** (b) The period **T** (c) The frequency **f** (d) At what times is the object at $x = 0$?

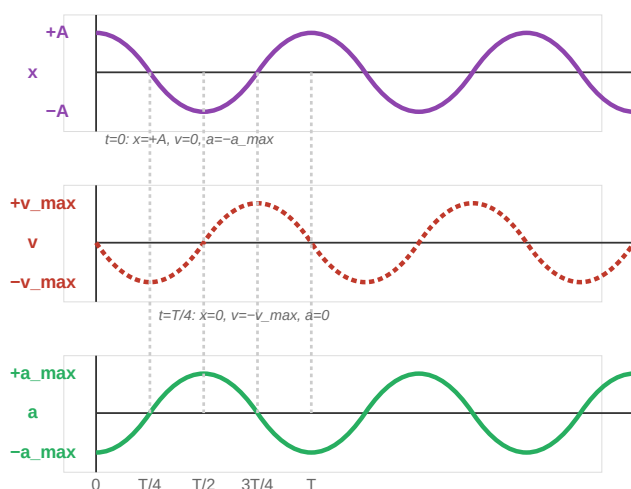
PHASE RELATIONSHIPS: X, V, AND A

THE KEY RELATIONSHIPS

$$v_{\max} = \frac{2\pi A}{T} = A\omega \quad \text{where} \quad \omega = \frac{2\pi}{T}$$

$$a_{\max} = \left(\frac{2\pi}{T}\right)^2 A = A\omega^2$$

- **v is maximum** when $x = 0$ (passing through the center)
- **v is zero** when $x = \pm A$ (momentarily stopping at turning points)
- **a is maximum** when $x = \pm A$ (maximum stretch = maximum restoring force)
- **a is zero** when $x = 0$ (at equilibrium, no restoring force)



Key insight: Notice that the peaks of the velocity graph happen right as position crosses zero. They are **OPPOSITE** — not in sync! At the endpoints, the object stops momentarily ($v = 0$) before reversing. At the center, it is moving fastest.

UNIVERSALITY & THE SMALL ANGLE ASSUMPTION

A system undergoes simple harmonic motion when its net force is a linear restoring force, $F = -kx$, over the range of motion. A mass on a spring satisfies this exactly in our ideal model; a pendulum satisfies it only for small angles. Let's check whether a pendulum obeys this condition.

THE SMALL ANGLE TRICK

For a pendulum, gravity pulls down, but the string forces it to swing in an arc. The component of gravity pulling it *back to the center* is:

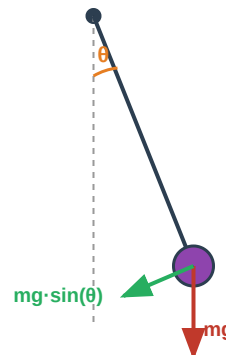
$$F_{\text{restore}} = -mg \sin(\theta)$$

Because of the $\sin(\theta)$, the force is **not** perfectly proportional to displacement. A pendulum is not perfectly SHM!

BUT... if θ is small (less than 15°), $\sin(\theta) \approx \theta$ (when measured in radians). Since arc length $x = L\theta$, we can substitute $\theta = x/L$:

$$F_{\text{restore}} \approx -mg \left(\frac{x}{L} \right) = - \left(\frac{mg}{L} \right) x$$

This matches Hooke's Law ($F = -kx$) perfectly! The pendulum's **"effective spring constant"** is $k = mg/L$.



The Math Trick: If we substitute the effective spring constant $k = \frac{mg}{L}$ into the spring period formula $T = 2\pi\sqrt{\frac{m}{k}}$, we get $T = 2\pi\sqrt{\frac{m}{mg/L}} = 2\pi\sqrt{\frac{L}{g}}$. Notice the mass cancels out entirely!

CONCEPT Exercise 2: Proving the Approximation

Let's test it. If $\theta = 10^\circ$:

(a) Convert 10° to radians (multiply by $\pi/180$).

(b) Calculate $\sin(10^\circ)$ in degree mode.

Are they close? What if you try it with 45° ?

YOU DO Exercise 3: Effective Spring Constant

A 0.50 kg pendulum bob hangs from a 1.2 m string. What is its "effective spring constant"? What is its period of oscillation?

